

Pipeline Girth Welds Inspection Using Automated Ultrasonic Testing (AUT) with Zonal Discrimination – Simulation of POD Curves Using CIVA Software

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Abstract

The inspection of pipeline girth welds can be performed by automated ultrasonic testing systems composed of several channels (different transducers or multi-element probes with a set of different focal laws). These systems allow, with a single scan along the circumference of the pipe, a complete examination of the weld using the zonal discrimination approach. However, the use of these systems is subjected to the demonstration of their performances confronted to realistic degradations of their environment. This demonstration is synthesized in a qualification dossier and is supported by experimental sensitivity analysis to several influencing factors (pipe temperature, error in the positioning of the sensors...) and POD curves determination. This requires a large amount of experiments.

In order to reduce the cost and time required today to determine a POD curve for a given inspection method simulation can be used.

Simulations of typical girth welds inspection configurations using CIVA software are performed. Many influencing factors can be taken into account in CIVA such as the material and geometry of the specimen, the location, orientation and geometry of the flaw, the orientation and the position of the probe compared to the weld and the pipe temperature. Uncertainty propagation is performed using a Monte Carlo sampling strategy to get POD curves. In accordance to the DNV recommended practices a cumulative lognormal distribution is used to approximate POD curves based on Hit/Miss data. Purely numerical POD curves can therefore be obtained for a single channel and for the global inspection system. The whole computation scheme to get the numerical POD curves using CIVA software and its dedicated POD module is presented.



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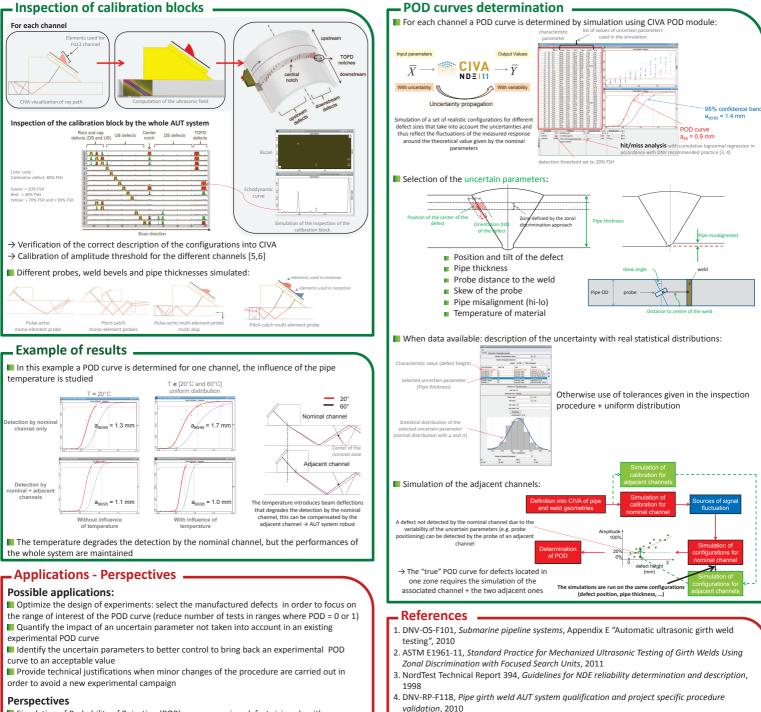
Context

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- A girth weld is the assembly of two pipelines for a subsea flowline
- As required by regulations (e.g. DNV-OS-F101 [1]) such welds have to be verified for integrity, the full volume of the weld must be inspected and flaw size shall be characterized

Automated Ultrasonic Testing (AUT) systems generate and propagate ultrasounds waves thanks to different monoelement transducers or a phased array transducers with different focal laws. Each transducer or focal law (= a channel) is dedicated to the inspection of a specific zone of the weld \rightarrow zonal discrimination [2]

The qualification of the system requires the demonstration of performance through the determination of a POD curve, which is a process long and costly and necessary for each modification of the inspection procedure (pipe thickness, weld geometry, ...) \rightarrow interest for simulation



Simulation of Probability of Rejection (POR) curves, requires defect sizing algorithm Redaction of a "Best Recommended Practice" document in the framework of IIW for the use of simulation for UT inspection of welds

Bayesian fusion of empirical/simulated data to increase reliability of POD curves and limit the number of experiments

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